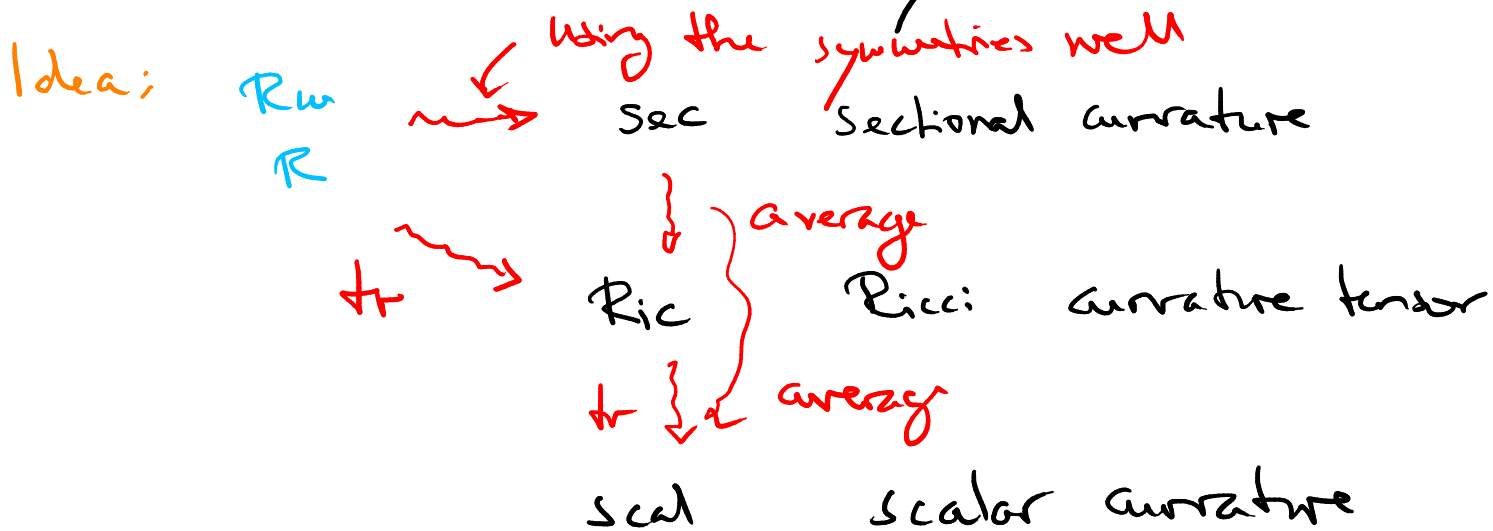


Recap: $R \mapsto R_{ij} = R^k_{ij}$

• characterisation of flat wfd

Goal: extract/forget information of the Ricm. curvature tensors in a convenient way.



2.4.3 SECTIONAL CURVATURE
DE: Schnittkrümmung

Idea: sectional curvature: tangent plane \mapsto real number
spanned by v, w
 $R_{ij}(v, w, w, v)$ scaled appropriately

Definition (sectional curvature). let (M, g) be a Ricm. wfd, let $x \in M$. Then the sectional curvature of (M, g) at x is def'd by: For all li. indep. pairs (v, w) with $v, w \in T_x M$:

$$\text{sec}_{x, g}^{M, g}(v, w) := \frac{R_{ij}(v, w, w, v)}{|v \wedge w|_g^2}$$

$$|v \wedge w|_g := \sqrt{\|v\|_g^2 \cdot \|w\|_g^2 - \langle v, w \rangle_g^2}$$

area of $\underbrace{v \wedge w}_{\substack{\text{parallelogram} \\ \text{spanned by } v, w}}$ > 0
CS

Example. Flat Riem. mfd's have constant sectional curvature 0.

Remark. If $\varphi: (M_1, g_1) \rightarrow (M_2, g_2)$ is a local isometry and $x \in M_1$, $v, w \in T_x M_1$, then
 $\sec_x^{M_1, g_1}(v, w) = \sec_{\varphi(x)}^{M_2, g_2}(d_x \varphi(v), d_x \varphi(w))$
 (Len and l.n.l.g are preserved by φ).

Proposition. Let (M, g) be a Riem. mfd, let $x \in M$ and let $(v, w), (\tilde{v}, \tilde{w})$ be two l.n. indep. pairs in $T_x M$ with $\text{span}_{\mathbb{R}}(v, w) = \text{span}_{\mathbb{R}}(\tilde{v}, \tilde{w})$.
 Then: $\sec(v, w) = \sec(\tilde{v}, \tilde{w})$.

Proof. Because of $\text{span}_{\mathbb{R}}(v, w) = \text{span}_{\mathbb{R}}(\tilde{v}, \tilde{w})$,
 there ex. $A = \begin{pmatrix} \alpha_v & \alpha_w \\ \beta_v & \beta_w \end{pmatrix} \in GL(2, \mathbb{R})$ s.t.
 $\tilde{v} = \alpha_v \cdot v + \beta_v \cdot w$ and
 $\tilde{w} = \alpha_w \cdot v + \beta_w \cdot w$.

Then:

$$|\tilde{v} \wedge \tilde{w}|_g^2 = |\det A|^2 \cdot |v \wedge w|_g^2$$

$= (\det A)^2$

$\cdot Rm(\tilde{v}, \tilde{w}, \tilde{w}, \tilde{v}) = \alpha_{\tilde{v}\tilde{w}} \cdot \alpha_{\tilde{w}\tilde{v}} \cdot Rm(v, w, v, w)$
 $(\det A)^2 \cdot Rm(v, w, w, v)$ + ... mixed terms
 symmetry of Rm $0 =$ + terms with $Rm(u, u, \dots, \dots)$
 or $Rm(\dots, \dots, u, u)$ \square

Proposition. (sectional curvature determines the Riem. curvature tensor). Let M be a smooth manifold and let R_1, R_2 be $(4,0)$ -tensor fields on M that satisfy the symmetries in Prop. 2.4.9 of the Riem. curvature tensor. Moreover, for all $x \in M$ and all lin. indep. $v, w \in T_x M$, we assume

$$R_1(v, w, w, v) = R_2(v, w, w, v).$$

Then: $R_1 = R_2$.

Proof. Look at $R_1 - R_2$ and use multilin. algebra \textcircled{L} 1.3. \square

Corollary. (flatness via sectional curvature).

A Riem. manifold is flat if and only if it has constant sectional curvature 0.

Proof. " \Rightarrow ": Clair (above example).

" \Leftarrow ": Apply the previous prop. to Rm and 0. \square

2.4.4 RICCI CURVATURE

idea: $R \xrightarrow{\text{tr}} \text{Ric}$

Definition. (Ricci curvature). Let (M, g) be a Riem. mfd. Then, the Ricci (curvature) tensor of (M, g) is the $(2, 0)$ -tensor field on M , def'd by

$$\text{Ric} : \Gamma(TM) \times \Gamma(TM) \rightarrow C^\infty(M)$$
$$(X, Y) \mapsto \text{tr} (Z \mapsto R(Z, X)Y)$$

Example. Flat mfds have constant Ricci curvature tensor 0.

Remark. Let (M, g) be a Riem mfd. Then Ric can be recovered from the map

$$TM \longrightarrow \mathbb{R}$$
$$T_x M \ni v \longmapsto \text{Ric}(v, v).$$

(1) 9.2.

Proposition. (Ricci via averaging of sec).

Let (M, g) be a Riem mfd of dim n , let $x \in M$, let $v \in T_x M$, and let (v_1, \dots, v_n) be an ONB of $T_x M$ with $v_1 = v$.

Then

$$\text{Ric}(v, v) = \sum_{k=2}^n \text{sec}(v_k, v_k).$$



Proof. We have

$$\text{Ric}(v, v) = \text{tr} (z \mapsto R(z, v, v))$$

use (v_1, \dots, v_n) to unfold tr \rightarrow $\sum_{k=1}^n v_k$ -contribution of $R(v_k, v, v)$

(v_1, \dots, v_n) ONB \rightarrow $\sum_{k=1}^n \langle R(v_k, v, v), v_k \rangle g$

$$= \sum_{k=1}^n \text{Rm}(v_k, v, v, v_k) = \frac{1}{\underbrace{\|v_k \wedge v\|_g^2}} = 1 \text{ as } (v_1, \dots, v_n) \text{ ONB}$$

because $v_i = v$ and symm of Rm \rightarrow

$$= \sum_{k=2}^n \text{sc}(v_k, v)$$

$= 1$ as (v_1, \dots, v_n) ONB \square

Remark. Ricci curvature is an invariant of local isometry.

2.4.5 SCALAR CURVATURE

idea: Ric $\xrightarrow{\text{or}}$ scal

Definition. (scalar curvature). Let (M, g) be a Riem. wfd. Then, the scalar curvature of (M, g)

is the smooth map

$$\text{scal}: M \rightarrow \mathbb{R}$$

$$x \mapsto \text{tr} (z \mapsto \text{Ric}_x^\#(z)).$$

Example. Flat wfd's have constant scalar curv. 0.

Proposition: (scal via averaging from sec). Let (M, g) be a Riem. mfd of dim n , let $x \in M$, and let (v_1, \dots, v_n) be an ONB of $T_x M$.

Then

$$\text{scal}(x) = \sum_{\substack{j, k \in \{1, \dots, n\} \\ j \neq k}} \text{sec}(v_j, v_k).$$

Proof. similar to the Ric-statement. \square

Remark. Local isometries preserve scalar curvature.

Proposition. Homogeneous Riemannian mfd's have constant scalar curvature.

Proof. Let (M, g) be a homogeneous Riem mfd and let $x, y \in M$.
 \hookrightarrow ex. $\varphi \in \text{Isom}(M, g)$ with $\varphi(x) = y$.

inv. of scal $\implies \text{scal}(x) = \text{scal}(\varphi(x)) = \text{scal}(y)$. \square

2.5 MODEL SPACES $\mathbb{R}^n, \mathbb{S}^n(\mathbb{R}), \mathbb{H}^n(\mathbb{R})$

goal: compute sec of all model spaces

idea: use: - high degree of symmetry \implies constant sec. curvature
 - locally conformally flat.

(2.5.1) LOCALLY CONFORMALLY FLAT MFDs

Definition.

- let \mathcal{M} be a smooth mfd. Riem. metrics g, \tilde{g} are conformal if there ex. an $f \in C^\infty(\mathcal{M}, \mathbb{R}_{>0})$ with

$$\tilde{g} = f \cdot g.$$

- A Riem. mfd (\mathcal{M}, g) is conformally flat if g is conformal to a flat Riem. metric on \mathcal{M} .

- A Riem. mfd (\mathcal{M}, g) is locally conformally flat, if every $x \in \mathcal{M}$ admits an open nbhd that is conformally flat (wrt. restriction of g).

Theorem. (Riem. curv. and conformal change).
let (\mathcal{M}, g) be a Riem. mfd of dim n ,
let $f \in C^\infty(\mathcal{M}, \mathbb{R}_{>0})$, and let $\tilde{g} := e^{2f} \cdot g$.
Then: locally, we have:

$$\tilde{\Gamma}_{ij}^k = \underbrace{\Gamma_{ij}^k}_{\text{original}} + \delta_{jk} \cdot E_i(f) + \delta_{ik} \cdot E_j(f)$$

$$\tilde{R}_{ijkl} = \underbrace{e^{2f} \cdot R_{ijkl}}_{\text{original}} - g_{ij} \cdot E_l(f) - g_{kl} \cdot E_j(f) + g_{il} \cdot E_k(f) + g_{kj} \cdot E_i(f)$$

$$- e^{2f} \cdot (g_{ik} \cdot T_{je} + g_{jk} \cdot T_{ie} - g_{ie} \cdot T_{jk} - g_{je} \cdot T_{ik})$$

where

$$T_{ij} := \nabla_{E_i} \nabla_{E_j} f - \nabla_{E_i} f \cdot \nabla_{E_j} f$$

$$+ \frac{1}{2} \cdot \underbrace{\|\text{grad } f\|_g^2}_{\text{with } g} \cdot g_{ij}$$

$$:= (df)^\# \in \Gamma(TM)$$

In particular: If $g = (\delta_{ij})_{i,j}$, then

$$\tilde{R}_{ijji} = 0 - e^{2f} \cdot (T_{jj} - T_{ii}).$$

Proof, computations... (L) 9.4. □